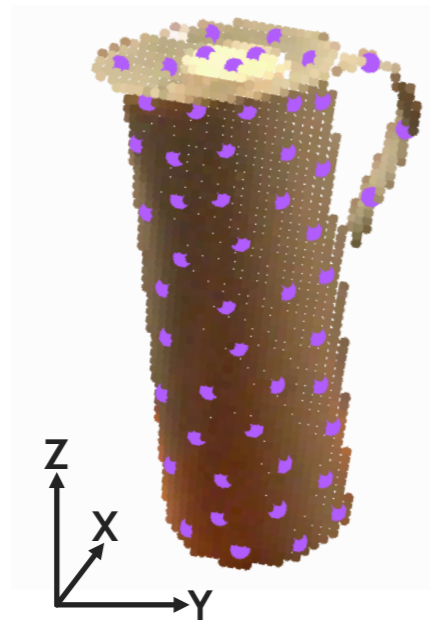


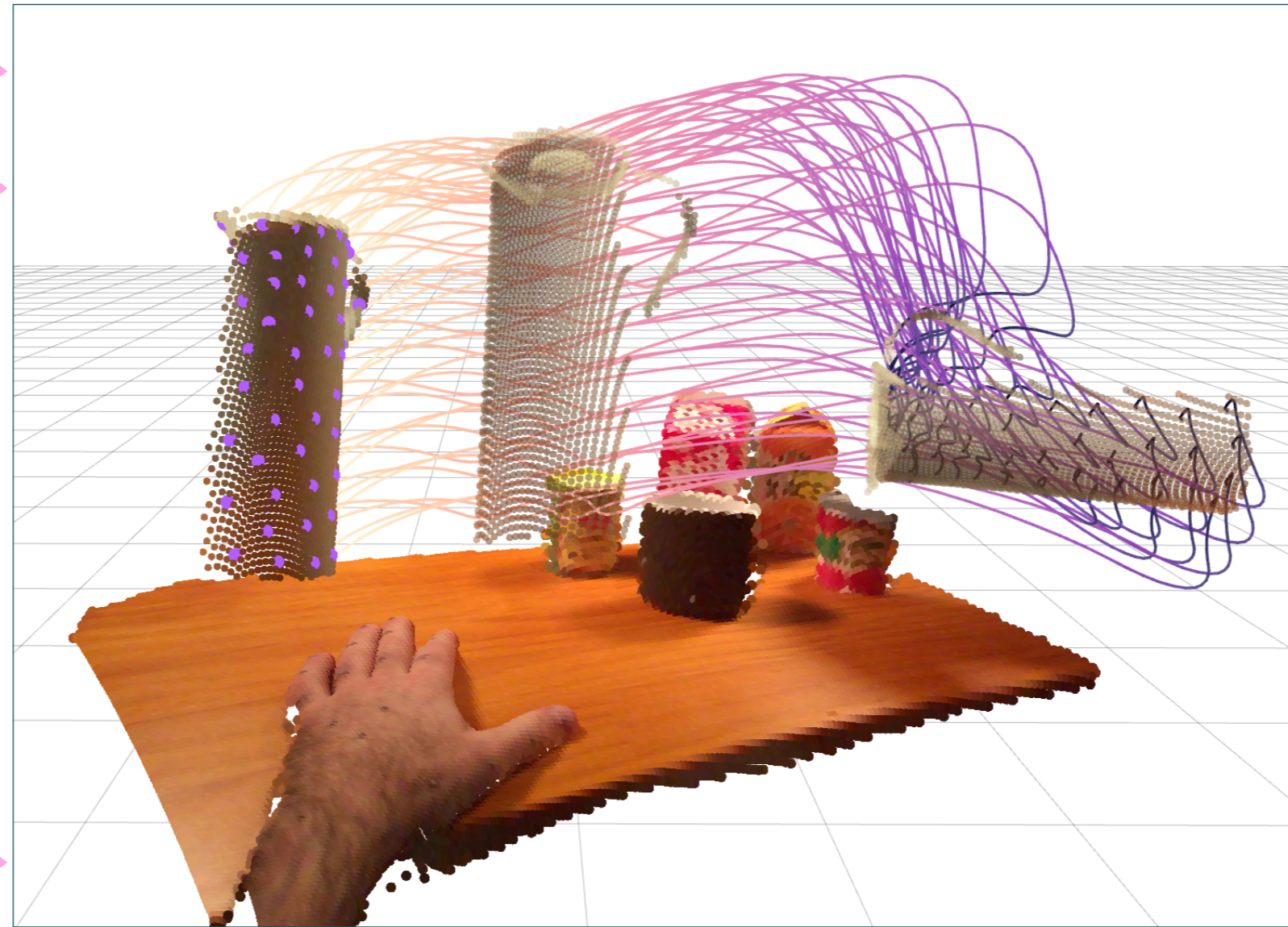
### RGB Observation



### Query Points



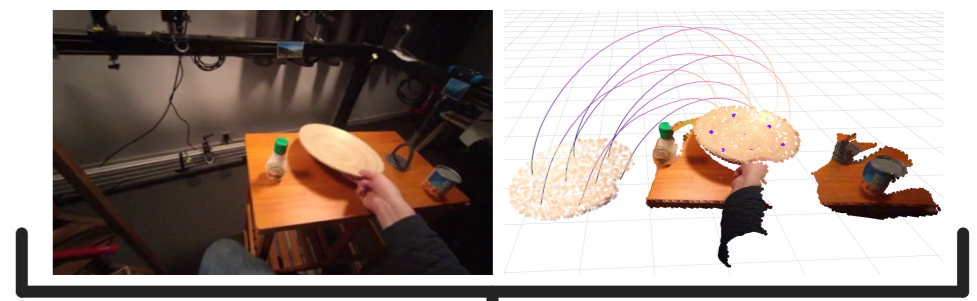
### Predicted Future 3D Point Trajectory



### Robotics Planning



### Trajectory-Conditioned Video Generation



**Action**  
*pour water from the tan flask into the red can*

Time

Time