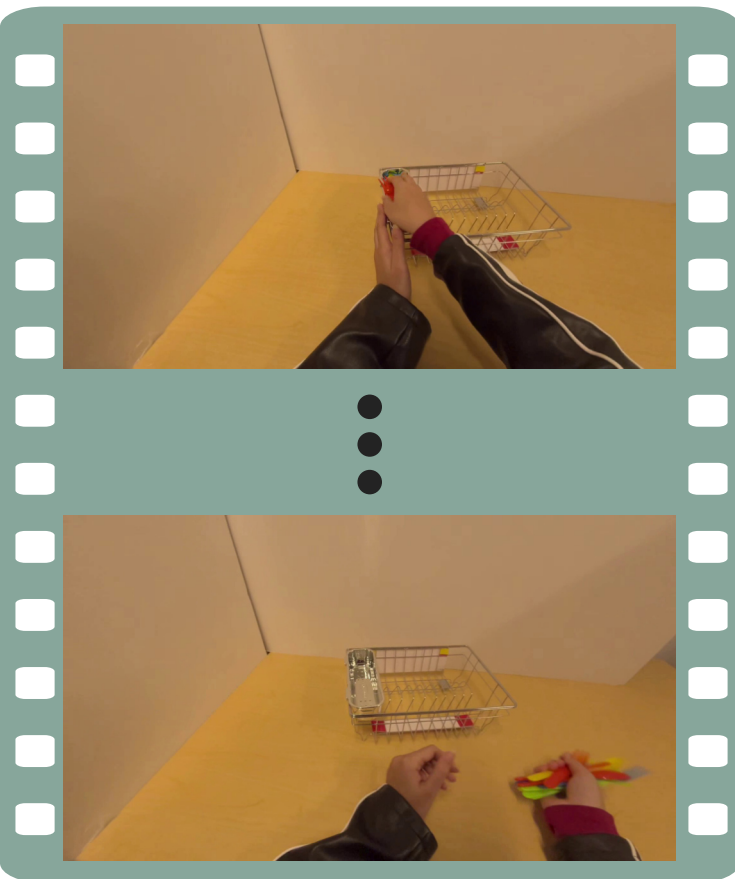


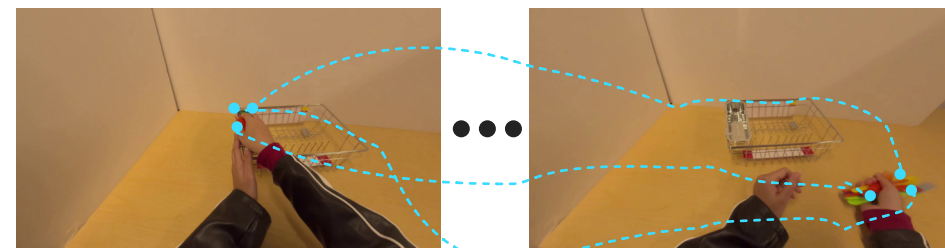
put the *utensils* in the silver container



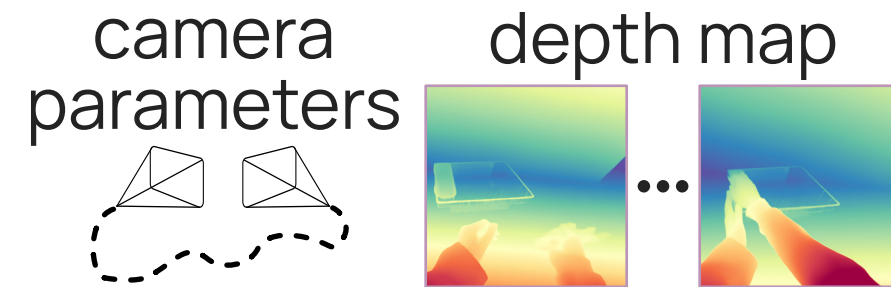
generate query points



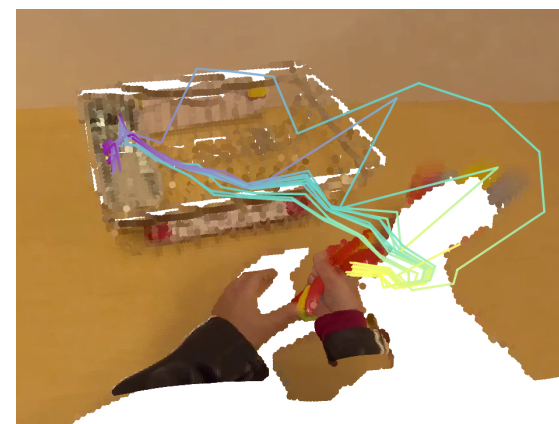
track 2D points



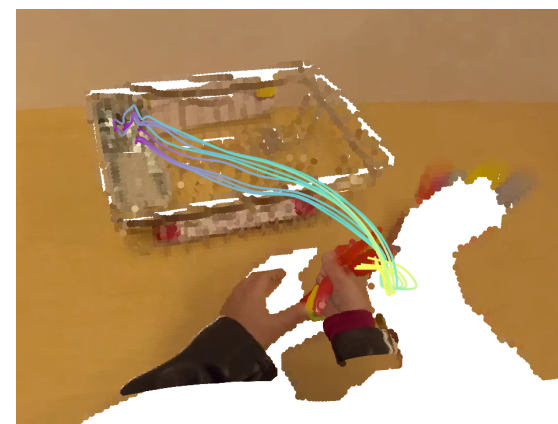
3D reconstruction



lift trajectories to 3D



refine trajectories



segment motion clip

