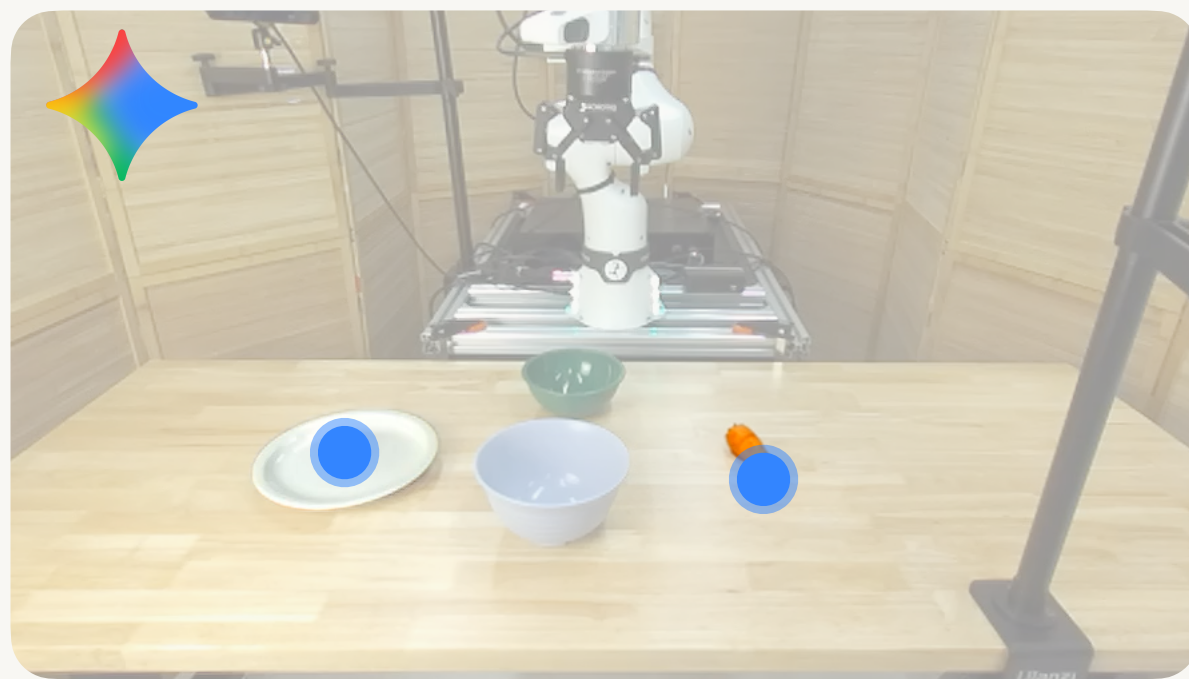


"Put the carrot on the plate"

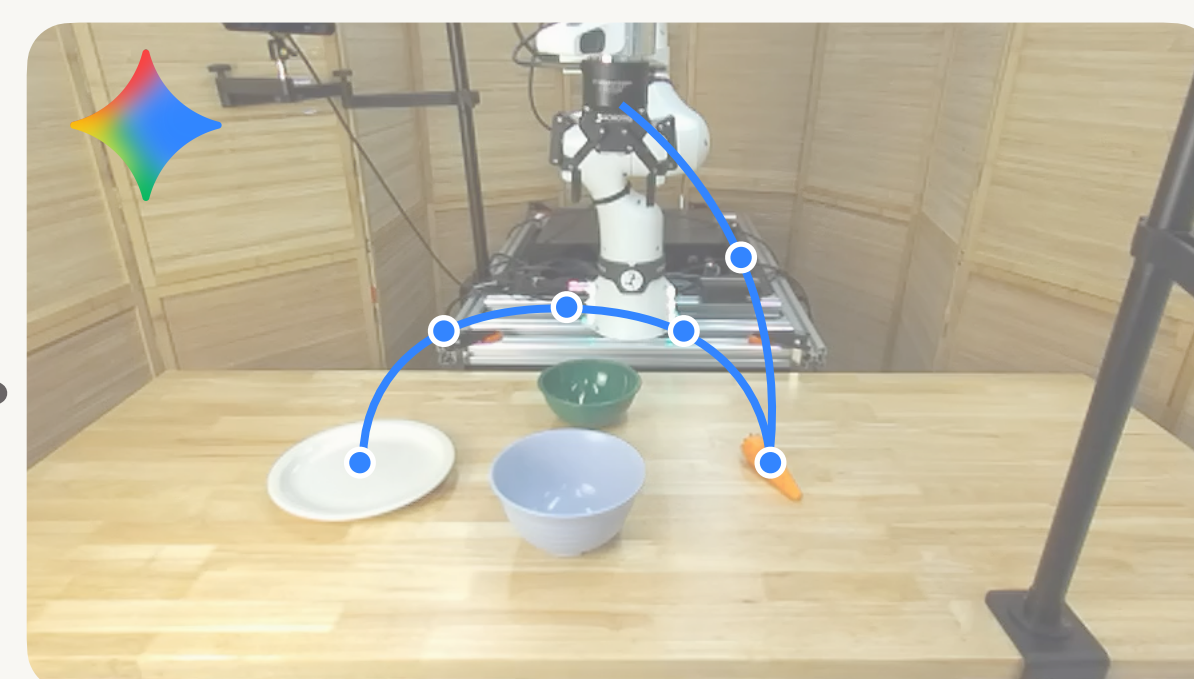
Initial Conditions


<Objects>:
{Carrot,
Plate}



<Source: Carrot>:{100, 200}, <Target: Plate>: {200, 300}

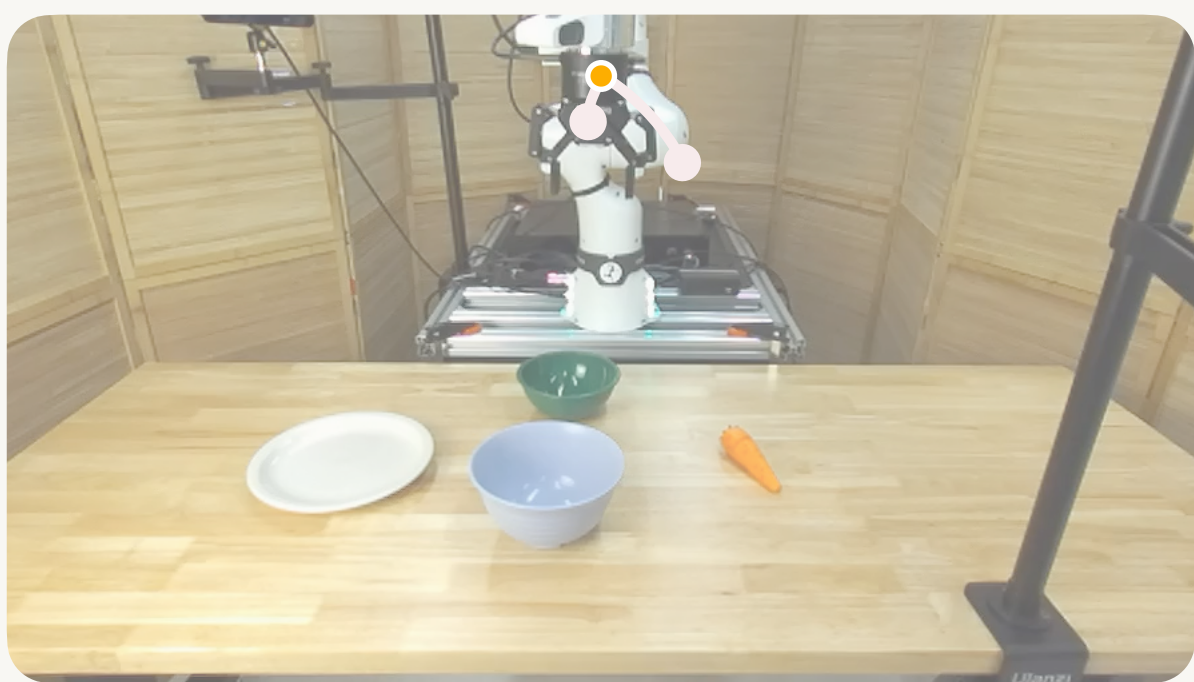
Object Initial Position



"uv": [100, 200], "min_hold": 200, "skippable": True

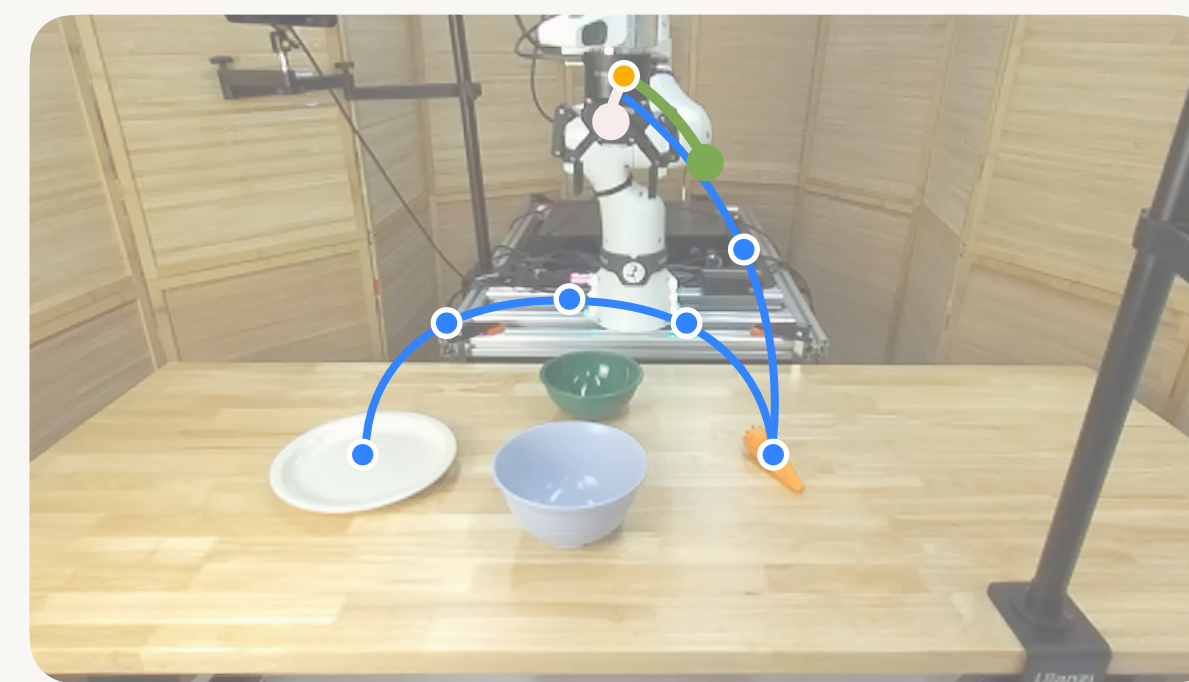
Proposed Execution Trace

Robot Generalist Policy

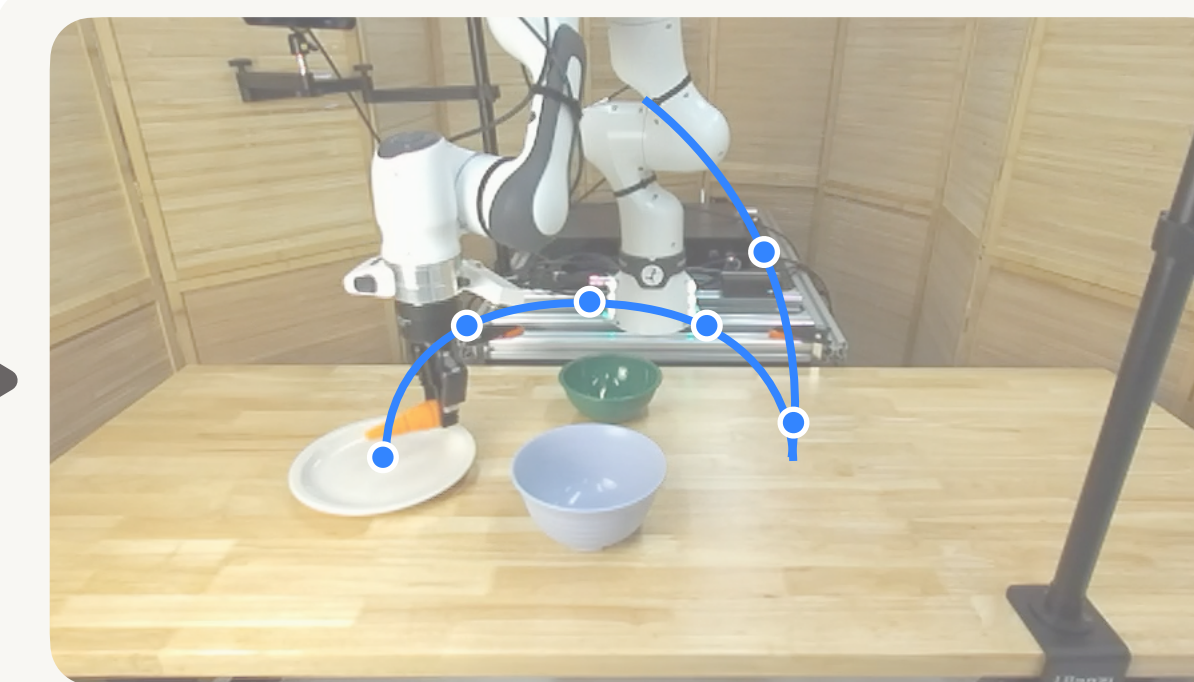


Policy as Proposer

*Action
Chunk as
Reasoning
Trace*



Visual Verification



Best-of-N Execution